Realtime 3D Computer Graphics & Virtual Reality



Bitmaps and Textures

Imaging and Raster Primitives

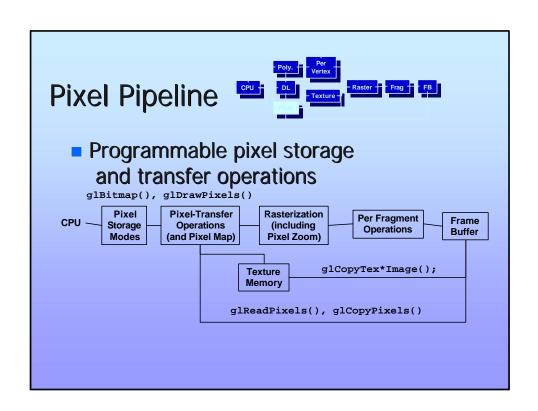
Vicki Shreiner

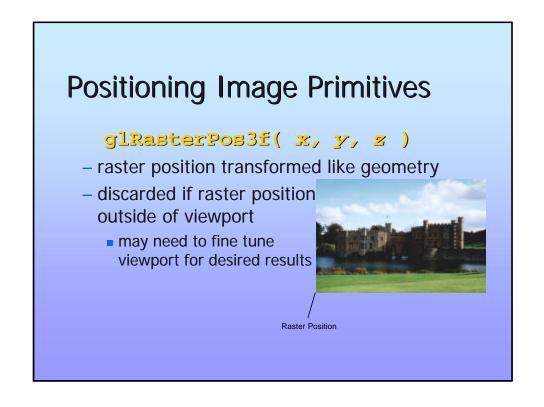
Imaging and Raster Primitives

- Describe OpenGL's raster primitives: bitmaps and image rectangles
- Demonstrate how to get OpenGL to read and render pixel rectangles

Pixel-based primitives

- Bitmaps
 - 2D array of bit masks for pixels
 - update pixel color based on current color
- Images
 - 2D array of pixel color information
 - complete color information for each pixel
- OpenGL doesn't understand image formats





Rendering Bitmaps

```
glBitmap( GLsizei width, GLsizei height, GLfloat xorig, GLfloat yorig, GLfloat xmove, GLfloat ymove, GLubyte *bitmap)

- render bitmap in current color at (x-x_{orig}, y-y_{orig})

- advance raster position by yorig (x_{move}, y_{move}) after rendering
```

Rendering Fonts using Bitmaps

- OpenGL uses bitmaps for font rendering
 - each character is stored in a display list containing a bitmap
 - window system specific routines to access system fonts
 - glXUseXFont()
 - wglUseFontBitmaps()

Rendering Images



- render pixels with lower left of image at current raster position
- numerous formats and data types for specifying storage in memory
 - best performance by using format and type that matches hardware

Reading Pixels

- read pixels form specified (x,y) position in framebuffer
- pixels automatically converted from framebuffer format into requested format and type
- Framebuffer pixel copy glCopyPixels(x, y, width, height, type)

Pixel Zoom

glPixelZoom(x, y)

- expand, shrink or reflect pixels around current raster position
- fractional zoom supported

Raster glPixelZoom(1.0, -1.0);



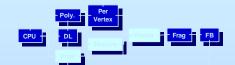
Storage and Transfer Modes

- Storage modes control accessing memory
 - byte alignment in host memory
 - extracting a subimage
- Transfer modes allow modify pixel values
 - scale and bias pixel component values
 - replace colors using pixel maps

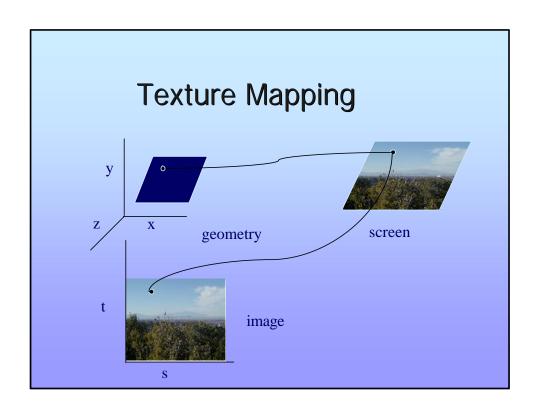
Texture Mapping

*(some taken from Ed Angel)

Texture Mapping

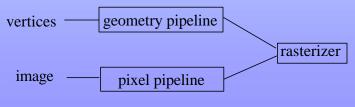


- Apply a 1D, 2D, or 3D image to geometric primitives
- Uses of Texturing
 - simulating materials
 - reducing geometric complexity
 - image warping
 - reflections

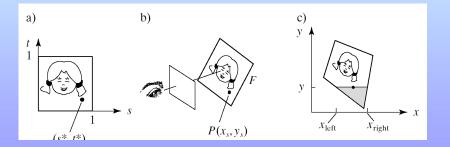


Texture Mapping and the OpenGL Pipeline

- Images and geometry flow through separate pipelines that join at the rasterizer
 - "complex" textures do not affect geometric complexity

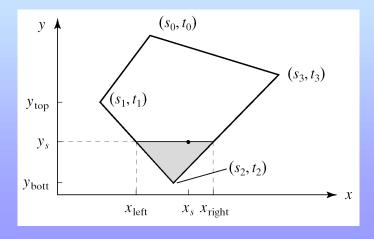


Rendering a texture

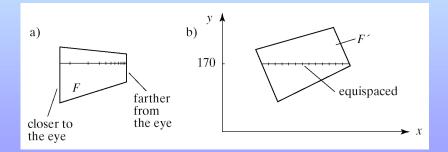


*Following pictures are courtesy of F.S.Hill Jr. "Computer Graphics using OpenGL 2nd"

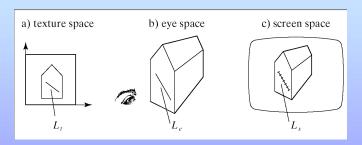
Rendering a texture: scanline



Rendering a texture: linear interpolation



Rendering a texture



- Affine and projective transformations preserve straightness.
- If moving equal steps across Ls, how to step in Lt?

Affine combination of two points

Given the linear combination of points $A = (A_1, A_2, A_3, 1)$ and $B = (B_1, B_2, B_3, 1)$ using the scalars s and t:

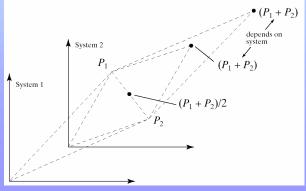
$$sA + tB = (sA_1 + tB_1, sA_2 + tB_2, sA_3 + tB_3, s + t)$$

This is a valid vector if s+t=0. It is a valid point if s+t=1.

- 1. If the coefficients of a linear combination sum to unity we call it an affine combination.
- 2. Any affine combination of points is a legitimate point. Why not building any linear combination of points P = sA + tB if s + t do not sum to unity?

Affine combination of two points

-> A shift of the origin is the problem, let's shift it by vector **v**, so *A* is shifted to *A*+**v** and *B* is shifted to *B*+**v**. If *P* is a valid point it must be shifted to *P*'=*P*+**v**! But we have *P*'=*sA*+*tB*+(*s*+*t*)**v**. This is not in general *P*+**v**, only if *s*+*t*=1!



Linear interpolation of two points

Let P be a point defined by a point A and a vector \mathbf{v} scaled by s and substitute \mathbf{v} with the difference of a point B and A.

$$P = A + s\mathbf{v} \iff P = A + s(B - A)$$

This can be rewritten as an affine combination of points as:

$$P = A + s(B - A) \Leftrightarrow P = sB + (1 - s)A$$

This performs a linear combination between points *A* and *B*!

For each component *c* of *P*, *Pc(s)* is the value which is the fraction *s* between *Ac* and *Bc*. This important operation has its own popular name *lerp()* (*linear interpolation*).

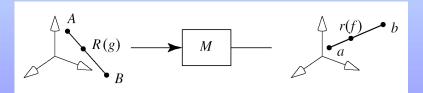
```
double lerp( double a, double b, double s){
  return ( a + (b - a) * s );}
```

Correspondence of motion along transformed lines

Let M be an affine or general perspective transformation.

The points A and B of a segment map to a and b.

The point R(g) maps to a point r(f).



How does g vary if f changes?

Why in the direction f->g? ->The process is to be embedded in the raster stage of the rendering pipeline!

Correspondence of motion along transformed lines

Let $\tilde{a} = (a_1, a_2, a_3, a_4)$ be the homogenous rep of a_i , therefore

$$a = \left(\frac{a_1}{a_4}, \frac{a_2}{a_4}, \frac{a_3}{a_4}\right)$$
 is calculated by perspective division.

$$M$$
 maps A to $a =$ $\widetilde{a} = M(A,1)^T$ and $\widetilde{b} = M(B,1)^T$

$$R(g) = lerp(A, B, g) \quad \text{maps to} \quad M(lerp(A, B, g), 1)^{T} = lerp(\widetilde{a}, \widetilde{b}, g)$$
$$= (lerp(a_1, b_1, g), lerp(a_2, b_2, g), lerp(a_3, b_3, g), lerp(a_4, b_4, g))$$

The latter being the homogenous coordinate version $\tilde{r}(f)$ of the point r(f).

Correspondence of motion along transformed lines

$$(lerp(a_1,b_1,g), lerp(a_2,b_2,g), lerp(a_3,b_3,g), lerp(a_4,b_4,g))$$

Component wise (for one comp.) perspective division results in

$$r_1(f) = \frac{lerp(a_1, b_1, g)}{lerp(a_4, b_4, g)}$$
 but we also have $r(f) = lerp(a, b, f)$

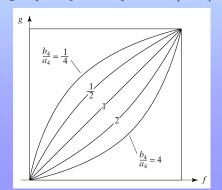
and hence (for one comp.)
$$r_1(f) = lerp\left(\frac{a_1}{a_4}, \frac{b_1}{b_4}, f\right)$$

resulting in
$$g = \frac{f}{lerp\left(\frac{b_4}{a_4}, 1, f\right)}$$

Correspondence of motion along transformed lines

$$g = \frac{f}{lerp\left(\frac{b_4}{a_4}, 1, f\right)}$$

 $g = \frac{f}{lerp\left(\frac{b_4}{a_4}, 1, f\right)}$ R(g) maps to r(f) with different fractions for f and g ! $g = f \Rightarrow f = 0 \lor f = 1 \lor b_4 = a_4$



Finding the point

The point R(g) that maps to r(f) is as follows (for one comp.):

$$R_{1} = \frac{lerp\left(\frac{A_{1}}{a_{4}}, \frac{B_{1}}{b_{4}}, f\right)}{lerp\left(\frac{1}{a_{4}}, \frac{1}{b_{4}}, f\right)}$$

Is there a difference if the matrix M is an affine or a perspective projection?

In the affine case, a_a and b_a are both unity and the relation between R(g) and r(f) degenerates to a linear dependency (remember the lerp() definition) and equal steps along ab correspond to equal steps along AB.

Finding the point

The perspective transformation case, given a matrix *M* (here the one that transforms from eye coordinates to clip coordinates):

$$M = \begin{bmatrix} N & 0 & 0 & 0 \\ 0 & N & 0 & 0 \\ 0 & 0 & c & d \\ 0 & 0 & -1 & 0 \end{bmatrix}$$
 Given a point A this leads to:
$$M(A,1)^{T} = (NA_{1}, NA_{2}, cA_{3} + d, -A_{3})$$

$$M(A,1)^{T} = (NA_{1}, NA_{2}, cA_{3} + d, -A_{3})$$

The last component $a_4 = -A_3$ is the position of the point along the z-axis -the view plane normal- in camera coordinates (depth of point in front of the eye).

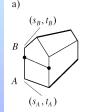
 $a_{\scriptscriptstyle A}, b_{\scriptscriptstyle A}$ interpreted as the depth represent a line parallel to the view plane if they are equal, hence there is no foreshortening effect.

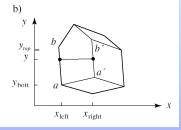
Texture processing during the scanline process: hyperbolic interpolation

We search for:

$$(s_{left}, t_{left})$$
 and (s_{right}, t_{right}) given:

$$f = (y - y_{bott}) / (y_{top} - y_{bott})$$





follows:
$$s_{(left)}(y) = \frac{lerp\left(\frac{s_A}{a_4}, \frac{s_B}{b_4}, f\right)}{lerp\left(\frac{1}{a_4}, \frac{1}{b_4}, f\right)}$$
 How does it look like for $t_{(left)}$
$$t_{(left)}(y) = \frac{lerp\left(\frac{t_A}{a_4}, \frac{t_B}{b_4}, f\right)}{lerp\left(\frac{1}{a_4}, \frac{1}{b_4}, f\right)}$$

$$lerp\left(\frac{1}{a_4}, \frac{1}{b_4}, f\right)$$

How does it look like for $t_{(left)}$?

$$t_{(left)}(y) = \frac{lerp\left(\frac{t_A}{a_4}, \frac{t_B}{b_4}, f\right)}{lerp\left(\frac{1}{a_4}, \frac{1}{b_4}, f\right)}$$

Texture processing during the scanline process: hyperbolic interpolation

$$s_{(left)}(y) = \frac{lerp\left(\frac{S_A}{a_4}, \frac{S_B}{b_4}, f\right)}{lerp\left(\frac{1}{a_4}, \frac{1}{b_4}, f\right)}$$

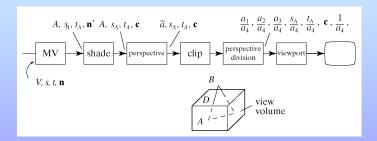
$$= \frac{lerp\left(\frac{1}{a_4}, \frac{1}{b_4}, f\right)}{lerp\left(\frac{1}{a_4}, \frac{1}{b_4}, f\right)}$$

- Same denominator for $s_{(left)}$ and $t_{(left)}$:
- Nominator is a linear interpolation of
- This is called rational linear rendering [Heckbert91] or hyperbolic interpolation [Blinn96].

Given y, the term $s_A/a_4, s_B/b_4, t_A/a_4, t_B/b_4, 1/a_4, 1/b_4$ is constant. Needed values for nominator and denominator can be found incrementally (see Gouraud shading).

Division is required for $S_{(left)}$ and $t_{(left)}$.

Scanline processing using hyperbolic interpolation in the pipeline



Each vertex V is associated with texture coords (s,t) and a normal \mathbf{n} . The modelview matrix M transforms into eye coords with $s_A = s, t_A = t$. Perspective transformation alters only A which results into \widetilde{a} . What happens during clipping?

Hyperbolic interpolation in the pipeline

During clipping a new point $D=(d_1,d_2,d_3,d_4)$ is created by $d_i = lerp(a_i,b_i,t), i=1,...4$, for some t.

The same is done for color and texture data. This creates a new vertex, for the given vertex we have the array

$$(a_1, a_2, a_3, a_4, s_A, t_A, c, 1)$$

Which finally undergoes perspective division leading to

$$(x, y, z, 1, s_A/a_A, t_A/a_A, c, 1/a_A)$$

What is (x,y,z)?

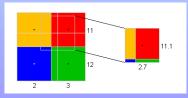
 \rightarrow (x,y,z) = position of point in normalized device coordinates.

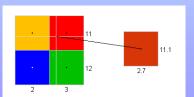
Why don't we devide c?

Hyperbolic interpolation in the pipeline

What happens now if we calculate (s,t) in the described way?

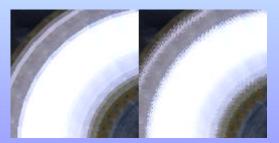
-> Referencing to "arbitrary" points into (s,t) space might further produce visual artifacts due to sampling errors.





Hyperbolic interpolation in the pipeline

Point sampling vs. bilinear filtering.



Texture Example

The texture (below) is a 256 x 256 image that has been mapped to a rectangular polygon which is viewed in perspective



Applying Textures I

- Three steps
 - Ospecify texture
 - read or generate image
 - assign to texture
 - ②assign texture coordinates to vertices
 - 3 specify texture parameters
 - wrapping, filtering

Applying Textures II

- specify textures in texture objects
- set texture filter
- set texture function
- set texture wrap mode
- set optional perspective correction hint
- bind texture object
- enable texturing
- supply texture coordinates for vertex
 - coordinates can also be generated

Texture Objects

- Like display lists for texture images
 - one image per texture object
 - may be shared by several graphics contexts
- Generate texture names

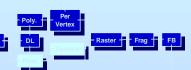
```
glGenTextures( n, *texIds );
```

Texture Objects (cont.)

- Create texture objects with texture data and state
- Bind textures before using

```
glBindTexture( target, id );
```

Specify Texture Image



 Define a texture image from an array of texels in CPU memory

```
glTexImage2D( target, level, components,
    w, h, border, format, type, *texels );
```

- dimensions of image must be powers of 2
- Texel colors are processed by pixel pipeline
 - pixel scales, biases and lookups can be done

Converting A Texture Image

If dimensions of image are not power of 2

```
gluScaleImage( format,
    w_in, h_in,type_in, *data_in,
    w out, h out,type out, *data out );
```

- *data_in is for source image
- *data_out is for destination image
- Image interpolated and filtered during scaling

Example

```
class RGB{ // holds a color triple - each with 256 possible
   intensities
   public: unsigned char r,g,b;
};

//The RGBpixmap class stores the number of rows and columns
//in the pixmap, as well as the address of the first pixel
//in memory:

class RGBpixmap{
  public:
   int nRows, nCols; // dimensions of the pixmap
   RGB* pixel; // array of pixels
   int readBMPFile(char * fname); // read BMP file into this
   pixmap
  void makeCheckerboard();
  void setTexture(GLuint textureName);
};
```

Example cont.

Example cont.

Specifying a Texture: Other Methods

- Use frame buffer as source of texture image
 - uses current buffer as source image

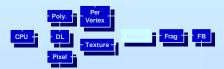
```
glCopyTexImage2D(...)
glCopyTexImage1D(...)
```

Modify part of a defined texture

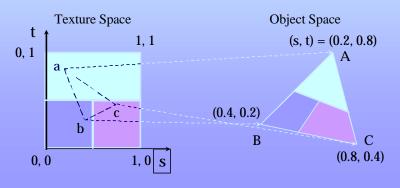
```
glTexSubImage2D(...)
glTexSubImage1D(...)
```

Do both with glCopyTexSubImage2D(...), etc.

Mapping a Texture



- Based on parametric texture coordinates
- glTexCoord*() specified at each vertex



Generating Texture Coordinates

Automatically generate texture coords

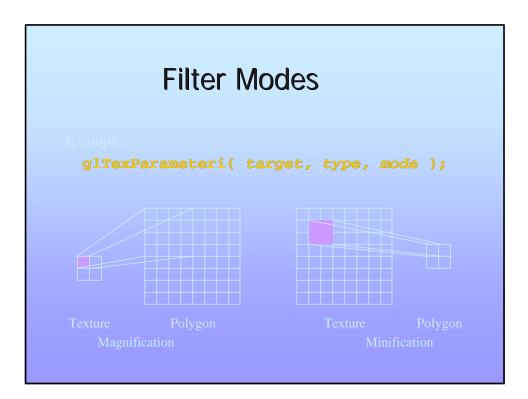
- specify a plane
 - generate texture coordinates based upon distance from plane Ax + By + Cz + D = 0
- generation modes
 - GL_OBJECT_LINEAR
 - GL_EYE_LINEAR
 - GL_SPHERE MAP

Tutorial: Texture



Texture Application Methods

- Filter Modes
 - minification or magnification
 - special mipmap minification filters
- Wrap Modes
 - clamping or repeating
- Texture Functions
 - how to mix primitive's color with texture's color
 - blend, modulate or replace texels



Mipmapped Textures

- Mipmap allows for prefiltered texture maps of decreasing resolutions
- Lessens interpolation errors for smaller textured objects
- Declare mipmap level during texture definition glTexImage*D(GL_TEXTURE_*D, level, ...)
- GLU mipmap builder routinesgluBuild*DMipmaps(...)
- OpenGL 1.2 introduces advanced LOD controls

Wrapping Mode

Example:







GL_REPEAT wrapping



GL_CLAMP wrapping

Texture Functions

Controls how texture is applied

- GL_TEXTURE_ENV_MODE modes
 - GL_MODULATE
 - GL_BLEND
 - GL_REPLACE
- Set blend color with
 GL_TEXTURE_ENV_COLOR

Perspective Correction Hint

- Texture coordinate and color interpolation
 - either linearly in screen space
 - or using depth/perspective values (slower)
- Noticeable for polygons "on edge"

```
glHint(GL_PERSPECTIVE_CORRECTION_HINT, hint)
where hint is one of
```

- GL_DONT_CARE
- GL NICEST
- GL_FASTEST

Is There Room for a Texture?

- Query largest dimension of texture image
 - typically largest square texture
 - doesn't consider internal format size

```
glGetIntegerv( GL_MAX_TEXTURE_SIZE, &size
```

- Texture proxy
 - will memory accommodate requested texture size?
 - no image specified; placeholder
 - if texture won't fit, texture state variables set to 0
 - doesn't know about other textures
 - only considers whether this one texture will fit all of memory

Texture Residency

- Working set of textures
 - high-performance, usually hardware accelerated
 - textures must be in texture objects
 a texture in the working set is resident
 for residency of current texture, check
 GL TEXTURE RESIDENT state
- If too many textures, not all are residentcan set priority to have some kicked out first
 - establish 0.0 to 1.0 priorities for texture objects

Advanced OpenGL Topics

Dave Shreiner

Advanced OpenGL Topics

- Display Lists and Vertex Arrays
- Alpha Blending and Antialiasing
- Using the Accumulation Buffer
- Fog
- Feedback & Selection
- Fragment Tests and Operations
- Using the Stencil Buffer